

Variational aspects of singular Liouville systems

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Singular Liouville systems

I considered **Singular Liouville systems** on a compact surface (Σ, g) :

$$-\Delta u_i = \sum_{j=1}^N a_{ij} \rho_j \left(\frac{h_j e^{u_j}}{\int_{\Sigma} h_j e^{u_j} dV_g} - 1 \right) - 4\pi \sum_{m=1}^M \alpha_{im} (\delta_{\rho_m} - 1), \quad i = 1, \dots, N.$$

- $A = (a_{ij})_{i,j=1}^N$ symmetric positive definite $N \times N$ matrix,
- $\rho_1, \dots, \rho_N > 0$,
- $0 < h_1, \dots, h_N \in C^\infty(\Sigma)$,
- $p_1, \dots, p_M \in \Sigma$,
- $\alpha_{11}, \dots, \alpha_{NM} > -1$,
- Without loss of generality $|\Sigma| = 1$.

Singular Liouville systems

Motivations

Such systems arise from different fields:

- **Statistical mechanics** (Chern-Simons vortices theory)
- **Physics of particles** (Kinetic plasma models)
- **Algebraic Geometry** (Complex holomorphic curves)
- **Biology** (Chemotaxis)

Singular Liouville systems

A change of variables

We re-write the system in an equivalent form:

Consider the solution of

$$\begin{cases} -\Delta G_p = \delta_p - 1 \\ \int_{\Sigma} G_p dV_g = 0 \end{cases}$$

and apply the change of variable

$$u_j \rightarrow u_j + 4\pi \sum_{m=1}^M \alpha_{jm} G_{p_m}$$

Singular Liouville systems

A change of variables

The new u solve

$$-\Delta u_i = \sum_{j=1}^N a_{ij} \rho_j \left(\frac{\tilde{h}_j e^{u_j}}{\int_{\Sigma} \tilde{h}_j e^{u_j} dV_g} - 1 \right) \quad \tilde{h}_i := h_i e^{-4\pi \sum_{m=1}^M \alpha_{im} G_{p_m}}$$

Singular Liouville systems

A change of variables

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Since $G_p = \frac{1}{2\pi} \log \frac{1}{d(\cdot, p)} + O(1)$ around p , then

$$\tilde{h}_i \sim d(\cdot, p_m)^{2\alpha_{im}} \quad \text{around } p_m,$$

that is

$$\alpha_{im} > 0 \quad \Rightarrow \quad \tilde{h}_i \text{ goes to } 0 \text{ around } p_m$$

$$\alpha_{im} < 0 \quad \Rightarrow \quad \tilde{h}_i \text{ goes to } +\infty \text{ around } p_m$$

Singular Liouville systems

The variational structure

In the last form, the problem has a **variational structure**: solutions are all and only the critical points of

$$J_\rho(u) := \frac{1}{2} \sum_{i,j=1}^N a^{ij} \int_\Sigma \nabla u_i \cdot \nabla u_j dV_g - \sum_{i=1}^N \rho_i \left(\log \int_\Sigma \tilde{h}_i e^{u_i} dV_g - \int_\Sigma u_i dV_g \right)$$

Singular Liouville systems

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If J_ρ is **coercive** (up to constants), then the system has minimizing solutions.

Existence of minimizing solutions

The scalar case

If $N = 1$,

$$-\Delta u = \rho \left(\frac{\tilde{h}e^u}{\int_{\Sigma} \tilde{h}e^u dV_g} - 1 \right)$$

and we have

$$I_{\rho}(u) := \frac{1}{2} \int_{\Sigma} |\nabla u|^2 dV_g - \rho \left(\log \int_{\Sigma} \tilde{h}e^u dV_g - \int_{\Sigma} u dV_g \right).$$

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It is well known that, setting with $\tilde{\alpha} := \min \left\{ 0, \min_m \alpha_m \right\}$

$\rho < 8\pi(1 + \tilde{\alpha}) \Rightarrow I_{\rho}$ coercive

$\rho = 8\pi(1 + \tilde{\alpha}) \Rightarrow I_{\rho}$ bounded from below but not coercive

$\rho > 8\pi(1 + \tilde{\alpha}) \Rightarrow I_{\rho}$ not bounded from below

Existence of minimizing solutions

Concentration-compactness alternative

We deduce that J_ρ is coercive for small ρ and we get minimizing solutions u_ρ .

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Existence of minimizing solutions

Concentration-compactness alternative

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What happens for higher values of ρ ?

We take a sequence u_{ρ_n} and discuss its convergence for $\rho_n \rightarrow \rho$.
If $u_{\rho_n} \rightarrow u_\rho$, then J_ρ must be coercive and u_ρ is a minimizer.

Existence of minimizing solutions

Concentration-compactness alternative

Concentration-compactness Theorem

Let $\{u_{\rho_n}\}_{\rho_n \rightarrow \rho}$ be a sequence of solutions with $\int_{\Sigma} \tilde{h}_i e^{u_{i,\rho_n}} dV_g = 1$.

Then,

$$\mathcal{S}_i := \{x \in \Sigma : \exists x_n \rightarrow x \text{ such that } u_{i,\rho_n}(x_n) \rightarrow +\infty\}$$

is finite for all i 's. Moreover,

- Either $\mathcal{S} := \bigcup_{i=1}^N \mathcal{S}_i = \emptyset$, and $u_{\rho_n} \rightarrow u_{\rho}$ in $W^{2,q}(\Sigma)^N$;
- Or $\mathcal{S} \neq \emptyset$, for each i , either $u_{i,\rho_n} \rightarrow u_i$ in $W_{loc}^{2,q}(\Sigma \setminus \mathcal{S})$ or $u_{i,\rho_n} \rightarrow -\infty$ in $L_{loc}^{\infty}(\Sigma \setminus \mathcal{S})$; the latter occurs for at least one i .

Existence of minimizing solutions

Concentration-compactness alternative

Define, for $x \in \mathcal{S}_i$,

$$\sigma_i(x) := \lim_{r \rightarrow 0} \lim_{n \rightarrow +\infty} \rho_{i,n} \int_{B_r(x)} \tilde{h}_i e^{u_{i,\rho_n}} dV_g.$$

Existence of minimizing solutions

Concentration-compactness alternative

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Then,

$$\rho_i \geq \sum_{x \in \mathcal{S}_i} \sigma_i(x);$$

$$\rho_i = \sum_{x \in \mathcal{S}_i} \sigma_i(x) \iff u_{i,\rho_n} \rightarrow -\infty \text{ in } L_{loc}^\infty(\Sigma \setminus \mathcal{S}).$$

Existence of minimizing solutions

Concentration-compactness alternative

If $x \in \mathcal{S}_i$ for $i \in \mathcal{I}$, then

$$\Lambda_{\mathcal{I},x}(\sigma(x)) := 8\pi \sum_{i \in \mathcal{I}} (1 + \alpha_i(x)) \sigma_i(x) - \sum_{i,j \in \mathcal{I}} a_{ij} \sigma_i(x) \sigma_j(x) = 0$$

where
$$\alpha_i(x) = \begin{cases} \alpha_{im} & \text{if } x = p_m \\ 0 & \text{otherwise} \end{cases}$$

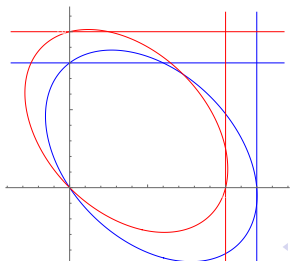
Existence of minimizing solutions

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Existence of minimizing solutions

Conditions for coercivity

Since $\sigma_i(x) \leq \rho_i$, blow-up cannot occur if $\Lambda_{\mathcal{I},x}(\rho) > 0$ for all \mathcal{I}, x .

Existence of minimizing solutions

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Setting $\Lambda(\rho) := \min_{\mathcal{I},x} \Lambda_{\mathcal{I},x}(\rho)$, we get:

B.-Malchiodi, 2014 - B., preprint

$$\Lambda(\rho) > 0 \quad \Rightarrow \quad J_\rho \text{ coercive}$$

Existence of minimizing solutions

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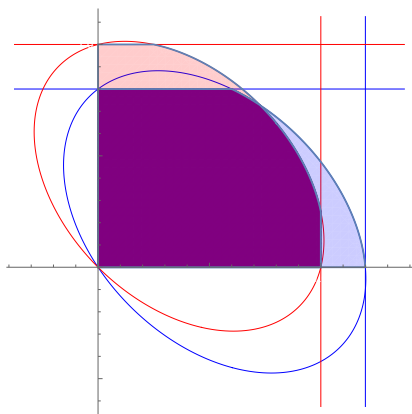
$$\Lambda(\rho) = 0 \Rightarrow J_\rho \text{ not coercive}$$

$$\Lambda(\rho) < 0 \Rightarrow J_\rho \text{ not coercive nor bounded from below}$$

Existence of minimizing solutions

Conditions for coercivity

The set $\Lambda > 0$:



Existence of minimizing solutions

Competitive systems

Suppose now $a_{ij} \leq 0$ for all $i \neq j$.

Then,

$$\Lambda(\rho) = \min_{i=1, \dots, N} (8\pi(1 + \tilde{\alpha}_i)\rho_i - a_{ii}\rho_i^2),$$

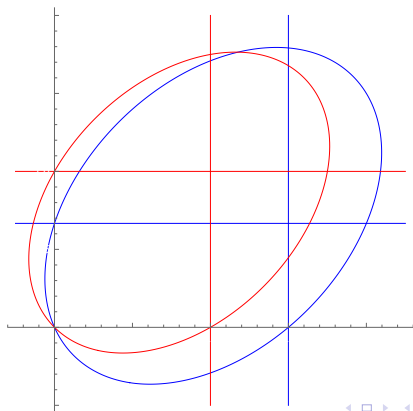
with

$$\tilde{\alpha}_i = \min_x \alpha_i(x) = \min \left\{ 0, \min_m \alpha_{im} \right\}$$

Existence of minimizing solutions

Competitive systems

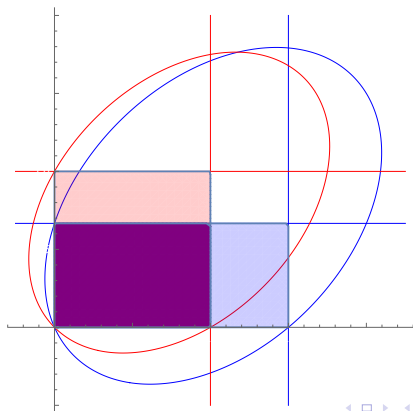
The set $\Lambda(\rho) > 0 = \left\{ \rho_i < \frac{8\pi(1 + \tilde{\alpha}_i)}{a_{ij}} \right\}$:



Existence of minimizing solutions

Competitive systems

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Existence of minimizing solutions

Competitive systems

For blowing-up sequences of minimizers for $\rho_{i,n} \rightarrow \frac{8\pi(1 + \tilde{\alpha}_i)}{a_{ii}}$,
 $\mathcal{S}_i = \{x_i\}$ and either $a_{ij} = 0$ or $x_i \neq x_j$ for all $i \neq j$.

Existence of minimizing solutions

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By the scalar Moser-Trudinger inequality we get a sharp result.

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B.-Malchiodi, 2014 - B., preprint

$\Lambda(\rho) > 0 \Rightarrow J_\rho$ coercive

$\Lambda(\rho) = 0 \Rightarrow J_\rho$ not coercive but **bounded from below**

$\Lambda(\rho) < 0 \Rightarrow J_\rho$ not coercive nor bounded from below

Min-max solutions

The role of sub-levels

If $\Lambda(\rho) < 0$, we cannot have minimizers.

We have to look for **min-max** critical points.

Min-max solutions

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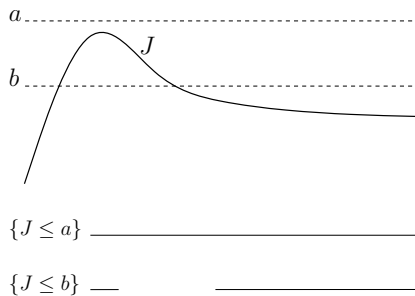
We will study the **topology of sub-levels** $\{J_\rho \leq a\}$:

No critical points with $a \leq J_\rho \leq b \Rightarrow \{J_\rho \leq a\} \simeq \{J_\rho \leq b\}$

$\{J_\rho \leq a\} \not\simeq \{J_\rho \leq b\} \Rightarrow$ Critical points with $a \leq J_\rho \leq b$

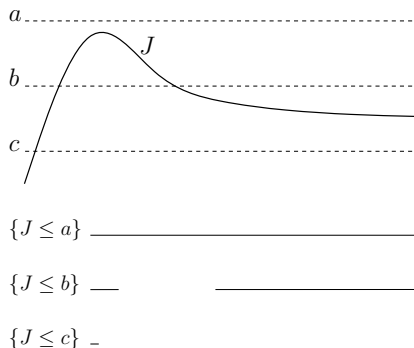
Min-max solutions

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Min-max solutions

The role of sub-levels



We need some **compactness conditions**.

Min-max solutions

Compactness issues

In general, such compactness conditions are not known, except for some particular systems.

Min-max solutions

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$$A_2 := \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

$$B_2 := \begin{pmatrix} 2 & -1 \\ -2 & 2 \end{pmatrix}$$

$$G_2 := \begin{pmatrix} 2 & -1 \\ -3 & 2 \end{pmatrix}$$

$$\alpha_{im} \equiv 0$$

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Min-max solutions

Compactness issues

Although B_2, G_2 are not symmetric, we can argue in the same way:

$$\begin{cases} -\Delta u_1 = 2\rho_1 \left(\frac{h_1 e^{u_1}}{\int_{\Sigma} h_1 e^{u_1} dV_g} - 1 \right) - 2 \cdot \frac{\rho_2}{2} \left(\frac{h_2 e^{u_2}}{\int_{\Sigma} h_2 e^{u_2} dV_g} - 1 \right) \\ -\Delta u_2 = -2\rho_1 \left(\frac{h_1 e^{u_1}}{\int_{\Sigma} h_1 e^{u_1} dV_g} - 1 \right) + 4 \cdot \frac{\rho_2}{2} \left(\frac{h_2 e^{u_2}}{\int_{\Sigma} h_2 e^{u_2} dV_g} - 1 \right) \end{cases}$$

$$\begin{aligned} J_{\rho}(u) &= \int_{\Sigma} \left(\frac{|\nabla u_1|^2}{2} + \frac{\nabla u_1 \cdot \nabla u_2}{2} + \frac{|\nabla u_2|^2}{4} \right) dV_g \\ &\quad - \rho_1 \left(\log \int_{\Sigma} h_1 e^{u_1} dV_g - \int_{\Sigma} u_1 dV_g \right) \\ &\quad - \frac{\rho_2}{2} \left(\log \int_{\Sigma} h_2 e^{u_2} dV_g - \int_{\Sigma} u_2 dV_g \right). \end{aligned}$$

The coercivity threshold is $\rho_1, \rho_2 < 4\pi$.



Min-max solutions

Compactness issues

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$$\begin{cases} -\Delta u_1 = 2\rho_1 \left(\frac{h_1 e^{u_1}}{\int_{\Sigma} h_1 e^{u_1} dV_g} - 1 \right) - 3 \cdot \frac{\rho_2}{3} \left(\frac{h_2 e^{u_2}}{\int_{\Sigma} h_2 e^{u_2} dV_g} - 1 \right) \\ -\Delta u_2 = -3\rho_1 \left(\frac{h_1 e^{u_1}}{\int_{\Sigma} h_1 e^{u_1} dV_g} - 1 \right) + 6 \cdot \frac{\rho_2}{3} \left(\frac{h_2 e^{u_2}}{\int_{\Sigma} h_2 e^{u_2} dV_g} - 1 \right) \end{cases}$$

$$\begin{aligned} J_{\rho}(u) &= \int_{\Sigma} \left(|\nabla u_1|^2 + \nabla u_1 \cdot \nabla u_2 + \frac{|\nabla u_2|^2}{3} \right) dV_g \\ &\quad - \rho_1 \left(\log \int_{\Sigma} h_1 e^{u_1} dV_g - \int_{\Sigma} u_1 dV_g \right) \\ &\quad - \frac{\rho_2}{3} \left(\log \int_{\Sigma} h_2 e^{u_2} dV_g - \int_{\Sigma} u_2 dV_g \right). \end{aligned}$$

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Min-max solutions

Compactness issues

Concerning A_2 , the coercivity threshold is $\rho_1, \rho_2 < 4\pi(1 + \tilde{\alpha}_i)$:

$$\begin{cases} -\Delta u_1 = 2\rho_1 \left(\frac{\tilde{h}_1 e^{u_1}}{\int_{\Sigma} \tilde{h}_1 e^{u_1} dV_g} - 1 \right) - \rho_2 \left(\frac{\tilde{h}_2 e^{u_2}}{\int_{\Sigma} \tilde{h}_2 e^{u_2} dV_g} - 1 \right) \\ -\Delta u_2 = -\rho_1 \left(\frac{\tilde{h}_1 e^{u_1}}{\int_{\Sigma} \tilde{h}_1 e^{u_1} dV_g} - 1 \right) + 2\rho_2 \left(\frac{\tilde{h}_2 e^{u_2}}{\int_{\Sigma} \tilde{h}_2 e^{u_2} dV_g} - 1 \right) \end{cases}$$

$$\begin{aligned} J_{\rho}(u) &= \int_{\Sigma} \frac{|\nabla u_1|^2 + \nabla u_1 \cdot \nabla u_2 + |\nabla u_2|^2}{3} dV_g \\ &- \rho_1 \left(\log \int_{\Sigma} \tilde{h}_1 e^{u_1} dV_g - \int_{\Sigma} u_1 dV_g \right) \\ &- \rho_2 \left(\log \int_{\Sigma} \tilde{h}_2 e^{u_2} dV_g - \int_{\Sigma} u_2 dV_g \right). \end{aligned}$$

Min-max solutions

Compactness issues

Jost-Lin-Wang, 2006 - Lin-Zhang, preprint

Assume $\alpha_{im} \equiv 0$ and $A = A_2, B_2$. Then, $\sigma_1(x), \sigma_2(x) \in 4\pi\mathbb{N}$.

The same holds true for $A = G_2$ if

$$\sigma_1(x) < 4\pi \left(2 + \sqrt{2}\right), \sigma_2(x) < 4\pi \left(5 + \sqrt{7}\right).$$

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Combining with concentration-compactness Theorem, we get

B.-Gabriele Mancini, 2015

Under the same assumptions, if blow-up occurs then

$$\rho \in \Gamma_0 := 4\pi\mathbb{N} \times \mathbb{R}_+ \cup \mathbb{R}_+ \times 4\pi\mathbb{N}.$$

Min-max solutions

Compactness issues

Similarly,

Lin-Wei-Zhang, 2015

Assume $A = A_2$. If $x \notin \{p_1, \dots, p_M\}$, then $\sigma_1(x), \sigma_2(x) \in 4\pi\mathbb{N}$, and $(\sigma_1(p_m), \sigma_2(p_m)) \in \Xi_m$ for some finite Ξ_m .

Therefore,

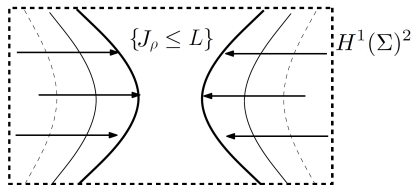
B.-Gabriele Mancini, 2015

Under the same assumptions, if blow-up occurs then $\rho \in \Gamma := \Gamma_1 \times \mathbb{R}_+ \cup \mathbb{R}_+ \times \Gamma_2$ for some discrete $\Gamma_1, \Gamma_2 \subset \mathbb{R}_+$

Min-max solutions

Compactness issues

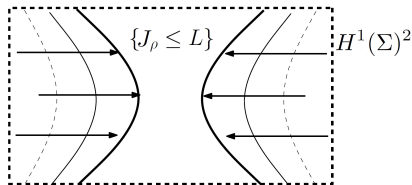
Moreover, $J_\rho \leq L$ for all solutions, so $\{J_\rho \leq L\}$ is a deformation retract of $H^1(\Sigma)^2$, hence it is **contractible**.



Min-max solutions

Compactness issues

Moreover, $J_\rho \leq L$ for all solutions, so $\{J_\rho \leq L\}$ is a deformation retract of $H^1(\Sigma)^2$, hence it is **contractible**.



Existence of solutions will follow if $\{J_\rho \leq -L\}$ is **not contractible** for large L .

Min-max solutions

Analysis of sub-levels

To prove that low sub-levels are not contractible, we “compare” it with a **not contractible** space \mathcal{X} in the following way:

$$\mathcal{X} \xrightarrow{\Phi} \{J_\rho \leq -L\} \xrightarrow{\Psi} \mathcal{X} \quad \Psi \circ \Phi \simeq \text{Id}_{\mathcal{X}}.$$

$\{J_\rho \leq -L\}$ is **dominated** by \mathcal{X} .

Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$

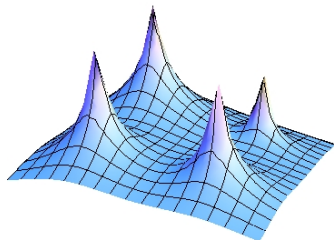
Let us consider the A_2 Toda system in the case $\alpha_{im} \geq 0$:

Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$

Let us consider the A_2 Toda system in the case $\alpha_{im} \geq 0$:

If $\rho_1 \in (4K_1\pi, 4(K_1 + 1)\pi)$, $\rho_2 \in (4K_2\pi, 4(K_2 + 1)\pi)$, then **either** u_1 concentrates at K_1 points **or** u_2 concentrates at K_2 points.



Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$

To express the concentration we use the **barycenters** on Σ :

$$(\Sigma)_K := \left\{ \sum_{k=1}^K t_k \delta_{x_k}; x_k \in \Sigma, t_k \geq 0, \sum_{k=1}^K t_k = 1 \right\}.$$

Min-max solutions

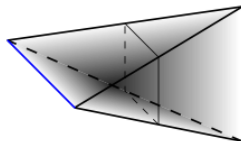
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To express the alternative between u_1 and u_2 , we use the **join**:

$$X \star Y := \{(1-t)x + ty; x \in X, y \in Y, t \in [0, 1]\}.$$



Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$

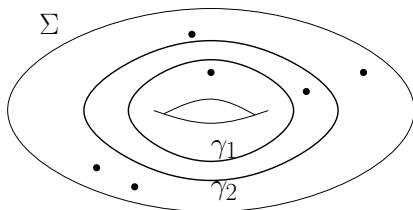
Two big issues are the concentration at singular points and concentration of both components at the same point.

Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$

Two big issues are the concentration at singular points and concentration of both components at the same point.

If $\chi(\Sigma) \leq 0$, this can be “by-passed” by a topological trick. There exist two **retractions** $\Pi_i : \Sigma \rightarrow \gamma_i$ for $i = 1, 2$ onto disjoint circles not containing any p_m .



Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$, $\chi(\Sigma) \leq 0$

Through Π_1, Π_2 , we can study the concentration of each u_j only on γ_j , avoiding interactions.

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Min-max solutions

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$$(\gamma_1)_{K_1} \star (\gamma_2)_{K_2} \simeq (\mathbb{S}^1)_{K_1} \star (\mathbb{S}^1)_{K_2} \simeq \mathbb{S}^{2K_1-1} \star \mathbb{S}^{2K_2-1} \simeq \mathbb{S}^{2K_1+2K_2-1}.$$

Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$, $\chi(\Sigma) \leq 0$

Through Π_1, Π_2 , we can study the concentration of each u_j only on γ_j , avoiding interactions.

We can take $\mathcal{X} := (\gamma_1)_{K_1} \star (\gamma_2)_{K_2}$, which is not contractible.

$$(\gamma_1)_{K_1} \star (\gamma_2)_{K_2} \simeq (\mathbb{S}^1)_{K_1} \star (\mathbb{S}^1)_{K_2} \simeq \mathbb{S}^{2K_1-1} \star \mathbb{S}^{2K_2-1} \simeq \mathbb{S}^{2K_1+2K_2-1}.$$

B.-Jevnikar-Malchiodi-Ruiz, 2015

Suppose $\rho \notin \Gamma$, $\chi(\Sigma) \leq 0$ and $\alpha_{im} \geq 0$ for all m . Then the A_2 Toda system has solutions.

Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$, $\chi(\Sigma) \leq 0$

The same results also works for the B_2 and G_2 Toda systems:

B., in preparation

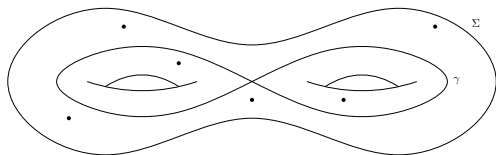
Suppose $\rho_1, \rho_2 \notin 4\pi\mathbb{N}$, $\chi(\Sigma) \leq 0$. Then the B_2 Toda system has solutions.

The same holds for the G_2 Toda system, provided $\rho_1 < 4\pi(2 + \sqrt{2})$, $\rho_2 < 4\pi(5 + \sqrt{7})$.

Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$, $\chi(\Sigma) \leq 0$

If Σ has genus $g = \left\lceil \frac{-\chi(\Sigma)}{2} \right\rceil + 1 \geq 2$, we can take γ_1, γ_2 as bouquet of g circles to get a generic multiplicity result via Morse theory:



Min-max solutions

Analysis of sub-levels, $\alpha_{im} \geq 0$, $\chi(\Sigma) \leq 0$

B., 2014 - B., in preparation

If $\rho_1 \in (4K_1\pi, 4(K_2 + 1)\pi)$, $\rho_2 \in (4K_2\pi, 4(K_2 + 1)\pi)$, then for a generic choice of g , h_1 , h_2 there are at least

$$\begin{pmatrix} K_1 + \left\lfloor \frac{-\chi(\Sigma)}{2} \right\rfloor \\ K_1 \end{pmatrix} \begin{pmatrix} K_2 + \left\lfloor \frac{-\chi(\Sigma)}{2} \right\rfloor \\ K_2 \end{pmatrix}$$

solutions.

Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

If we consider the A_2 Toda system without restrictions on α_{im} , the same argument fails because negative coefficients affect the M-T inequality.

Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

If we consider the A_2 Toda system without restrictions on α_{im} , the same argument fails because negative coefficients affect the M-T inequality.

To take account of this, we introduce the **weighted barycenters**:

$$\omega_i(q) = \begin{cases} 1 + \alpha_{im} & \text{if } q = p_m, \alpha_{im} < 0 \\ 1 & \text{otherwise} \end{cases} \quad \omega_i\left(\bigcup_k q_k\right) = \sum_k \omega_i(q_k)$$

$$(\Sigma)_{\rho_i, \underline{\alpha}_i} := \left\{ \sum_{x_k \in \mathcal{J}} t_k \delta_{x_k}; x_k \in \Sigma, t_k \geq 0, \sum_{x_k \in \mathcal{J}} t_k = 1, 4\pi \omega_i(\mathcal{J}) < \rho_i \right\}.$$

Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

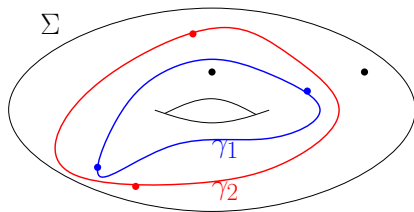
The topological argument can be adapted by modifying the retractions to take account of singularities.

Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

The topological argument can be adapted by modifying the retractions to take account of singularities.

We need $p_m \in \gamma_i$ if $\alpha_{im} < 0$, so we assume $\max\{\alpha_{1m}, \alpha_{2m}\} \geq 0$.



Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

Write:

$$\{p_1, \dots, p_M\} = \left\{ p'_{01}, \dots, p'_{0M'_0}, p'_{11}, \dots, p'_{1M'_1}, p'_{21}, \dots, p'_{2M'_2} \right\}$$

$$p_m = p'_{0m'} \iff \alpha_{1m}, \alpha_{2m} \geq 0 \iff p_m \notin \gamma_1 \cup \gamma_2$$

$$p_m = p'_{1m'} \iff \alpha'_{1m'} := \alpha_{1m} < 0 \iff p_m \in \gamma_1$$

$$p_m = p'_{2m'} \iff \alpha'_{2m'} := \alpha_{2m} < 0 \iff p_m \in \gamma_2$$

Min-max solutions

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This time, low sub-levels are dominated by the join of weighted barycenters $(\gamma_1)_{\rho_1, \underline{\alpha}_1} \star (\gamma_2)_{\rho_2, \underline{\alpha}_2}$.

Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

The weighted barycenters, hence their join, **could be contractible**.

Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

The weighted barycenters, hence their join, **could be contractible**.

This happens if

$$\sigma \in (\gamma_i)_{\rho_i, \underline{\alpha}_i} \Rightarrow (1-t)\sigma + t\delta_{p'_{i1}} \in (\gamma_i)_{\rho_i, \underline{\alpha}_i} \quad \forall t \in [0, 1];$$

which means, in terms of ρ ,

$$4\pi \left(K + \sum_{m \in \mathcal{M}} (1 + \alpha'_{im}) \right) < \rho_i \Rightarrow 4\pi \left(k + \sum_{m \in \mathcal{M} \cup \{1\}} (1 + \alpha'_{im}) \right) < \rho_i.$$

Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

If this does not happen for either i , then $(\gamma_1)_{\rho_1, \alpha_1} \star (\gamma_2)_{\rho_2, \alpha_2}$ is not contractible.

Min-max solutions

Analysis of sub-levels, $\chi(\Sigma) \leq 0$

If this does not happen for either i , then $(\gamma_1)_{\rho_1, \alpha_1} \star (\gamma_2)_{\rho_2, \alpha_2}$ is not contractible.

B. (2015)

Suppose $\rho \notin \Gamma$, $\chi(\Sigma) \leq 0$, $\max\{\alpha_{1m}, \alpha_{2m}\} \geq 0$ for all m and

$$4\pi \left(K_i + \sum_{m \in \mathcal{M}_i} (1 + \alpha'_{im}) \right) < \rho_i < 4\pi \left(K_i + \sum_{m \in \mathcal{M}_i \cup \{1\}} (1 + \alpha'_{im}) \right)$$

for some $K_1, K_2 \in \mathbb{N}$ and $\mathcal{M}_i \subset \{2, \dots, M'_i\}$.

Then the A_2 Toda system has solutions.

Min-max solutions

Analysis of sub-levels, general surfaces

In the general case, we need a sharper analysis.

Min-max solutions

Analysis of sub-levels, general surfaces

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Roughly speaking, in case of concentration at the same point with the **same rate**, the point must be given a higher weight.

Min-max solutions

Analysis of sub-levels, general surfaces

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Roughly speaking, in case of concentration at the same point with the **same rate**, the point must be given a higher weight.

If $\rho_1 < \bar{\rho}_1$, $\rho_2 < \bar{\rho}_2$, where

$$\bar{\rho}_j := 4\pi \min \left\{ 1, \min_{m \neq m'} (2 + \alpha_{im} + \alpha_{im'}) \right\},$$

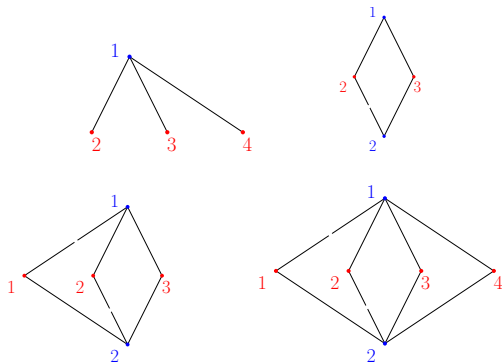
then low sub-levels are dominated by

$$\mathcal{X} = (\Sigma)_{\rho_1, \underline{\alpha}_1} \star (\Sigma)_{\rho_2, \underline{\alpha}_2} \setminus \left\{ \left(p_m, p_m, \frac{1}{2} \right) : \rho_1, \rho_2 < 4\pi(2 + \alpha_{1m} + \alpha_{2m}) \right\}.$$

Min-max solutions

Analysis of sub-levels, general surfaces

Since, for such ρ , both $(\Sigma)_{\rho_i, \underline{\alpha}_i}$ are finite, than \mathcal{X} is easy to study:



Min-max solutions

Analysis of sub-levels, general surfaces

We need some assumptions to get a not-contractible space:

B. (2015)

Suppose $\rho \notin \Gamma$, $\rho_i < \bar{\rho}_i$ for both i and

$(M_1, M_2, M_3) \notin \{(1, m, 0), (m, 1, 0), (2, 2, 1), (2, 3, 2), (3, 2, 2), m \in \mathbb{N}\}$,

with M_1, M_2, M_3 defined by

$$M_1 := \#\{m : 4\pi(1 + \alpha_{1m}) < \rho_1\},$$

$$M_2 := \#\{m : 4\pi(1 + \alpha_{2m}) < \rho_2\},$$

$M_3 := \#\{m : 4\pi(1 + \alpha_{im}) < \rho_i, \rho_i < 4\pi(2 + \alpha_{1m} + \alpha_{2m}) \text{ for both } i\}$.

Then the A_2 Toda system has solutions.



Non-existence results

General systems

We made topological assumptions on Σ to get general existence results.

In fact, if Σ has a “simple” topology, general systems could not be solvable.

Non-existence results

General systems

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In fact, if Σ has a “simple” topology, general systems could not be solvable.

On the standard unit disk we get, through a Pohožaev identity, **necessary** algebraic conditions.

Non-existence results

General systems

B.-Malchiodi, preprint

The following problem on the unit disk \mathbb{B} :

$$-\Delta u_i = \sum_{j=1}^N a_{ij} \rho_j \frac{|\cdot|^{2\alpha_j} e^{u_j}}{\int_{\mathbb{B}} |\cdot|^{2\alpha_j} e^{u_j} dx} \quad u_i|_{\partial\mathbb{B}} = 0 \quad i = 1, \dots, N,$$

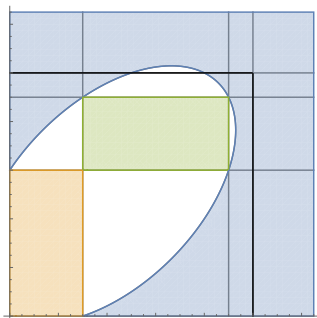
has no solutions if ρ satisfies

$$\Lambda_{\{1, \dots, N\}, \rho}(\rho) = 8\pi \sum_{i=1}^N (1 + \alpha_i) \rho_i - \sum_{i,j=1}^N a_{ij} \rho_i \rho_j \leq 0.$$

Non-existence results

General systems

Comparison with existence results for the A_2 Toda system:



Non-existence results

General systems

Similar results hold on the unit sphere with antipodal singularities:

B.-Malchiodi, preprint

The following problem on the unit sphere \mathbb{S}^2 :

$$-\Delta u_i = \sum_{j=1}^N a_{ij} \rho_j \left(\frac{e^{u_j}}{\int_{\mathbb{S}^2} e^{u_j} dV_g} - \frac{1}{4\pi} \right) - 4\pi \sum_{m=1}^2 \alpha_{im} \left(\delta_{p_m} - \frac{1}{4\pi} \right),$$

has no solutions if ρ satisfies:

$$\begin{array}{ll} \text{either} & \Lambda_{\mathcal{I}, p_1}(\rho) \geq \Lambda_{\{1, \dots, N\} \setminus \mathcal{I}, p_2}(\rho) & \forall \mathcal{I} \subset \{1, \dots, N\} \\ \text{or} & \Lambda_{\mathcal{I}, p_2}(\rho) \geq \Lambda_{\{1, \dots, N\} \setminus \mathcal{I}, p_1}(\rho) & \forall \mathcal{I} \subset \{1, \dots, N\} \end{array}$$

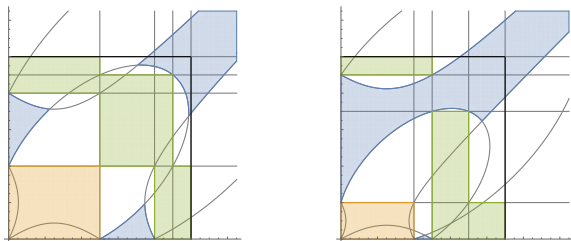
and at least one inequality is strict.



Non-existence results

General systems

Comparison with existence results for the A_2 Toda system:



Non-existence results

A_2 Toda system

We also get a non-existence results for the A_2 Toda system on **any** surface.

Non-existence results

A_2 Toda system

We also get a non-existence results for the A_2 Toda system on **any** surface.

If we take a couple of coefficients $(\alpha_{11}, \alpha_{21})$ close to -1 we show, through a blow-up analysis, that no solutions exist.

B.-Malchiodi, preprint

For any fixed $\alpha_{12}, \dots, \alpha_{1M}, \alpha_{22}, \dots, \alpha_{2M}$ and $\rho \notin \Gamma_{\frac{\alpha_{1\hat{1}}, \alpha_{2\hat{1}}}{\hat{1}}}$ there exists $\alpha^* \in (-1, 0)$ such that the A_2 Toda system has no solutions for $\alpha_{11}, \alpha_{21} \leq \alpha^*$.

THANK YOU FOR YOUR ATTENTION!